

Three-manifold invariants and their relation with the fundamental group

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Abstract. We consider the 3-manifold invariant $I(M)$ which is defined by means of the Chern-Simons quantum field theory and which coincides with the Reshetikhin-Turaev invariant. We present some arguments and numerical results supporting the conjecture that, for nonvanishing $I(M)$, the absolute value $|I(M)|$ only depends on the fundamental group $\pi_1(M)$ of the manifold M . For lens spaces, the conjecture is proved when the gauge group is $SU(2)$. In the case in which the gauge group is $SU(3)$, we present numerical computations confirming the conjecture.

1 Introduction

Recently, new 3-manifold invariants [1, 2] have been discovered; the algebraic aspects of their construction, which is based on the structure of simple Lie groups, are well understood [3, 4, 5, 6, 7, 8, 9]. However, the topological meaning of these invariants is still unclear. Let us denote by $I(M)$ the invariant of the 3-manifold M which is closed, connected and orientable; $I(M)$ is the invariant defined by means of the Chern-Simons quantum field theory [1, 9] and coincides with the Reshetikhin-Turaev invariant [2, 3]. In general, it is not known how $I(M)$ is related, for instance, to the homotopy class of M or to the fundamental group of M . In this article we shall formulate the following

Conjecture: for nonvanishing $I(M)$, the absolute value $|I(M)|$ only depends on the fundamental group $\pi_1(M)$.

In the absence of a general proof, we shall verify the validity of the conjecture for a particular class of manifolds: the lens spaces. There are examples of lens spaces M_1 and M_2 with the same fundamental group $\pi_1(M_1) \simeq \pi_1(M_2)$ which are not homeomorphic; for all these manifolds, we shall prove that (for nonvanishing invariants) $|I(M_1)| = |I(M_2)|$ when $I(M)$ is the invariant associated with the group $SU(2)$. In the case in which the gauge group is $SU(3)$, we will present numerical computations confirming the conjecture. Our results are in agreement with the computer calculations for $SU(2)$ of Freed and Gompf [10] and the expression of the $SU(2)$ invariant obtained by Jeffrey [11]. Differently from [10] and [11], our approach is based exclusively on the properties of 3-dimensional Chern-Simons quantum field theory. We shall use general surgery rules to compute $I(M)$ and, in our construction, invariance under Kirby moves is manifestly satisfied.

Our notations and conventions are described in section 2. The expression of the invariant $I(M)$ for a generic lens space is derived in section 3 and, for the gauge group $SU(2)$, the validity of our conjecture is proved in section 4. The numerical computations for the group $SU(3)$ are reported in section 5 and the conclusions are contained in section 6.

2 Surgery rules

The basic ingredient in the construction of the 3-manifold invariant $I(M)$ is a polynomial invariant $E(\mathcal{L})$ for oriented, framed and coloured links $\{\mathcal{L}\} \subset S^3$. In the Chern-Simons field theory, this link invariant is defined by the expectation values of the Wilson line operators [1]; each link component is framed and its colour is given by an irreducible representation of a simple compact Lie group which is called the gauge group. For example, when the gauge group is $SU(N)$ and each link component has colour corresponding to the fundamental representation of $SU(N)$, $E(\mathcal{L})$ is determined by the skein relation [1, 12]

$$q^{1/(2N)} E(\mathcal{L}_+) - q^{-1/(2N)} E(\mathcal{L}_-) = (q^{1/2} - q^{-1/2}) E(\mathcal{L}_0) \quad , \quad (1)$$

where $q = \exp(-i2\pi/k)$ is the deformation parameter and k is the renormalized coupling constant of the Chern-Simons field theory. The standard skein-related links \mathcal{L}_+ , \mathcal{L}_- and \mathcal{L}_0 correspond to a configuration with over-crossing, under-crossing and no-crossing respectively. Moreover, under an elementary ± 1 modification of the framing of a link component, $E(\mathcal{L})$ gets multiplied by the factor $q^{\pm(N^2-1)/2N}$. Finally, the factorization property [1, 12] which holds for the distant union of links fixes the normalization of the unknot with preferred framing

$$E_0[\text{fund.}] = (q^{N/2} - q^{-N/2}) / (q^{1/2} - q^{-1/2}) \quad . \quad (2)$$

In general, the colour which characterizes one link component is an element of the algebra \mathcal{T} which coincides with the complex extension of the representation ring of the gauge group. The sum operation in this algebra extends by linearity to $E(\mathcal{L})$; whereas the product operation in the colour algebra \mathcal{T} simply corresponds to the satellites obtained from the companion links by standard cabling [6, 13]. For unitary groups, the fundamental skein relation (1), the normalization (2) of the unknot and the correspondence between cabled components and higher-dimensional representations of the gauge group uniquely determine the values of the link invariant $E(\mathcal{L})$ for arbitrary coloured link components.

Let us denote by $\mathcal{L}_1 \# \mathcal{L}_2[\rho]$ the connected sum of the links \mathcal{L}_1 and \mathcal{L}_2 in which the component which connects these two links has colour given by the irreducible representation ρ of the gauge group. From the properties of the Chern-Simons field theory it follows that [1, 13]

$$E(\mathcal{L}_1 \# \mathcal{L}_2[\rho]) = \frac{E(\mathcal{L}_1) E(\mathcal{L}_2)}{E_0[\rho]} \quad , \quad (3)$$

where $E_0[\rho]$ is the value of the unknot with preferred framing and colour ρ .

For integer values of the Chern-Simons coupling constant k ($k = 1, 2, 3, \dots$), the set of vanishing link invariants defines an ideal \mathcal{I}_k of \mathcal{T} . Thus, for fixed integer k , the colour states belong to the algebra [13] of the equivalence classes

$$\mathcal{T}_{(k)} = \mathcal{T} / \mathcal{I}_k \quad . \quad (4)$$

Usually, $\mathcal{T}_{(k)}$ is of finite order [14] and, for appropriate values of k , $\mathcal{T}_{(k)}$ is isomorphic with the Verlinde algebra [15] which is determined by the fusion rules of certain two-dimensional conformal models [1]. We shall now concentrate on $\mathcal{T}_{(k)}$ when the gauge group G is $SU(2)$ [13] or $SU(3)$ [16]. For $G = SU(2)$ and $k = 1$, $\mathcal{T}_{(1)}$ is isomorphic with the group algebra of Z_2 , which is the center of $SU(2)$. For $G = SU(2)$ and $k \geq 2$, the ideal \mathcal{I}_k is generated by the representation with $J = (k-1)/2$ and $\mathcal{T}_{(k)}$ is of order $(k-1)$. For $G = SU(3)$ and $k = 1, 2$, the algebra (4) is isomorphic with the group algebra of Z_3 , which is the center of $SU(3)$. For $G = SU(3)$ and $k \geq 3$, the ideal \mathcal{I}_k is generated by the two irreducible representations with Dynkin labels $(k-1, 0)$ and $(k-2, 0)$; in this case, $\mathcal{T}_{(k)}$ is of order $(k-1)(k-2)/2$.

We shall denote by $\{\psi[i]\}$ (with $i = 1, 2, \dots, \dim(\mathcal{T}_{(k)})$) the elements of a basis in $\mathcal{T}_{(k)}$. When $G = SU(2)$ and $k \geq 2$ or when $G = SU(3)$ and $k \geq 3$, each

$\psi[i]$ represents the equivalence class of an irreducible representation of the gauge group. For low values of k , $\psi[i]$ corresponds to an irreducible representation of the gauge group up to a nontrivial multiplicative factor [13, 16]. The unit in $\mathcal{T}_{(k)}$ will be denoted by $\psi[1]$; $\psi[1]$ is the class defined by the trivial representation.

Let us now consider the definition of the 3-manifold invariant $I(M)$. Each 3-manifold M , which is closed, connected and orientable, admits a surgery presentation [17] given by Dehn surgery on S^3 . Each “honest” [17] surgery instruction can be represented by a framed link $\mathcal{L} \subset S^3$ with components $\{\mathcal{L}_b\}$ with $b = 1, 2, \dots$. The surgery link \mathcal{L} is not oriented and an integer surgery coefficient r_b is attached to the component \mathcal{L}_b . The framing \mathcal{L}_{bf} of \mathcal{L}_b is specified by the linking number

$$\ell k(\mathcal{L}_b, \mathcal{L}_{bf}) = r_b \quad . \quad (5)$$

The surgery link associated to the manifold M is not unique. Indeed, if the surgery links \mathcal{L} and \mathcal{L}' are related by a finite sequence of Kirby moves, the corresponding manifolds are homeomorphic [18]. Therefore, each 3-manifold M is characterized by a class of “equivalent” surgery links in S^3 , where “equivalent” links means links related by Kirby moves.

Let $\mathcal{L} \subset S^3$ be a surgery link for the manifold M . The invariant $I(M)$ is defined in terms of the expectation value $E(\mathcal{L})$ of the Wilson line operators associated with the surgery link \mathcal{L} . More precisely, one introduces an (arbitrary) orientation and a particular colour state Ψ_0 for each component of \mathcal{L} . For fixed integer k , the surgery colour state $\Psi_0 \in \mathcal{T}_{(k)}$ is [2]

$$\Psi_0 = a_k \sum_i E_0[i] \psi[i] \quad , \quad (6)$$

where the sum is performed over all the elements $\{\psi[i]\}$ of the basis of $\mathcal{T}_{(k)}$. The coefficients $\{E_0[i]\}$ coincide with the expectation values of the unknot with preferred framing and colour $\psi[i]$. When the gauge group G is $SU(2)$, a_k is given by [13]

$$a_k = \begin{cases} 1/\sqrt{2} & k = 1 \\ \sqrt{\frac{2}{k}} \sin(\pi/k) & k \geq 2 \end{cases} \quad ; \quad (7)$$

whereas, when $G = SU(3)$, one has [16]

$$a_k = \begin{cases} 1/\sqrt{3} & k = 1, 2 \\ 16 \cos(\pi/k) \sin^3(\pi/k)/(k\sqrt{3}) & k \geq 3 \end{cases} \quad . \quad (8)$$

We shall denote by $\sigma(\mathcal{L})$ the signature of the linking matrix associated with \mathcal{L} ; $\sigma(\mathcal{L})$ does not depend on the choice of the orientation of \mathcal{L} . Let us define the function $I(\mathcal{L})$ by means of the relation [2]

$$I(\mathcal{L}) = \exp[i\theta_k \sigma(\mathcal{L})] E(\mathcal{L}) \quad , \quad (9)$$

where, for $G = SU(2)$, the phase factor $e^{i\theta_k}$ is [2, 13]

$$e^{i\theta_k} = \begin{cases} \exp(-i\pi/4) & k = 1 \\ \exp[i\pi 3(k-2)/(4k)] & k \geq 2 \end{cases} \quad ; \quad (10)$$

and, for $G = SU(3)$, the phase factor is [16]

$$e^{i\theta_k} = \begin{cases} \exp(i\pi/2) & k = 1 \\ \exp(-i\pi/2) & k = 2 \\ \exp(-i6\pi/k) & k \geq 3 \end{cases} . \quad (11)$$

It can be verified [2, 3, 13, 16] that $I(\mathcal{L})$ is invariant under Kirby moves and then it represents a topological invariant for the 3-manifold M . In what follows, we shall denote this invariant by $I(M)$.

It should be noted that the multiplicative phase factor in (9) is not a matter of convention (or choice of framing); the presence of the term $\exp[i\theta_k \sigma(\mathcal{L})]$ in (9) guarantees the invariance of $I(\mathcal{L})$ under Kirby moves. According to the definition (9), the normalization of the 3-manifold invariant $I(M)$ is fixed by $I(S^3) = 1$.

In order to compare $I(M)$ with the expressions obtained in [10, 11], we need to produce the relation between the link invariants and the representation matrices of the mapping class group of the torus.

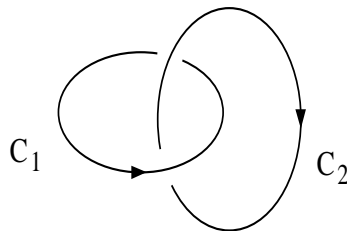


Figure 1

Let us consider the Hopf link in S^3 , shown in Figure 1; let the two link components C_1 and C_2 have preferred framings and colours $\psi[i]$ and $\psi[j]$ respectively. The associated Chern-Simons expectation value is denoted by

$$H_{ij} = E(C_1, \psi[i]; C_2, \psi[j]) \quad . \quad (12)$$

The complex numbers $\{H_{ij}\}$ where $i, j = 1, 2, \dots, \dim(\mathcal{T}_{(k)})$ can be understood as the matrix elements of the so-called Hopf matrix H . Note that H is symmetric and that $E_0[i] = H_{1i} = H_{i1}$. Let $Q(i)$ be the value of the quadratic Casimir operator of the irreducible representation of the gauge group which is associated with an element of the class $\psi[i]$. One can show [14] that the matrices

$$X_{ij} = a_k H_{ij} \quad ; \quad Y_{ij} = q^{Q(i)} \delta_{ij} \quad ; \quad C_{ij} = \delta_{ij^*} \quad . \quad (13)$$

give a projective representation of the modular group

$$X^2 = C \quad ; \quad (14)$$

$$(XY)^3 = e^{-i\theta_k} C \quad . \quad (15)$$

This representation is isomorphic with the representation obtained in two-dimensional conformal field theories [1]; X corresponds to the S matrix of the conformal models and Y is the analogue of the T matrix.

3 Lens Spaces

Lens spaces, which are characterized by two integers p and r , will be denoted by $\{L_{p/r}\}$. The fundamental group of $L_{p/r}$ is Z_p . Two lens spaces $L_{p/r}$ and $L_{p'/r'}$ are homeomorphic if and only if $|p| = |p'|$ and $r = \pm r' \pmod{p}$ or $rr' = \pm 1 \pmod{p}$. Thus, we only need [17] to consider the case in which $p > 1$ and $0 < r < p$; moreover, r and p are relatively prime. The lens spaces $L_{p/r}$ and $L_{p'/r'}$ are homotopic if and only if $|p| = |p'|$ and $rr' = \pm$ quadratic residue \pmod{p} . Consequently, one can find examples of lens spaces which are homotopic but are not homeomorphic; for instance, $L_{13/2}$ and $L_{13/5}$. One can also find examples of lens spaces which are not homeomorphic and are not homotopic but have the same fundamental group; for instance, $L_{13/2}$ and $L_{13/3}$.

One possible surgery instruction corresponding to the lens space $L_{p/r}$ is given the unknot [17] with rational surgery coefficient (p/r) . From this surgery presentation one can derive [17] a “honest” surgery presentation of $L_{p/r}$ by using a continued fraction decomposition of the ratio (p/r)

$$\frac{p}{r} = z_d - \frac{1}{z_{d-1} - \frac{1}{\ddots - \frac{1}{z_1}}} \quad , \quad (16)$$

where $\{z_1, z_2, \dots, z_d\}$ are integers. The new surgery link \mathcal{L} corresponding to a “honest” surgery presentation of $L_{p/r}$ is a chain with d linked components, as shown in Figure 2, and the integers $\{z_1, z_2, \dots, z_d\}$ are precisely the surgery coefficients.

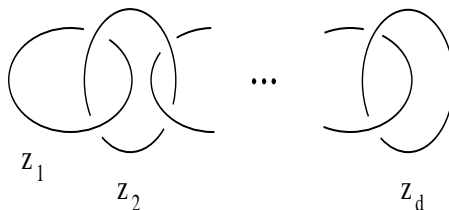


Figure 2

According to the definition (9), the lens space invariant is given by

$$I(L_{p/r}) = e^{i\theta_k \sigma(\mathcal{L})} (a_k)^d \sum_{j_1, \dots, j_d \in \mathcal{T}_k} \prod_{i=1}^d \left(q^{z_i Q(j_i)} \right) \times \\ \times E_0[j_1] \cdots E_0[j_d] E(\mathcal{L}; \psi[j_1], \dots, \psi[j_d]) \quad . \quad (17)$$

The link of Figure 2 can be understood as the connected sum of $(d-1)$ Hopf links \mathcal{H} , i.e. $\mathcal{L} = \mathcal{H} \# \mathcal{H} \cdots \# \mathcal{H}$. Therefore, by using equation (3), expression (17) can be written as

$$I(L_{p/r}) = e^{i\theta_k \sigma(\mathcal{L})} (a_k)^d \sum_{j_1, \dots, j_d \in \mathcal{T}_k} q^{\left(\sum_{i=1}^d z_i Q(j_i) \right)} H_{1j_d} H_{j_d j_{d-1}} \cdots H_{j_2 j_1} H_{j_1 1} \quad . \quad (18)$$

In terms of the generators (13) of the modular group, one finds

$$I(L_{p/r}) = e^{i\theta_k \sigma(\mathcal{L})} (a_k)^{-1} [F(p/r)]_{11} \quad , \quad (19)$$

where $[F(p/r)]_{11}$ is the element corresponding to the first row and the first column of the following matrix

$$F(p/r) = XY^{z_d} XY^{z_{d-1}} X \cdots XY^{z_1} X \quad . \quad (20)$$

The invariant $I(L_{p/r})$ given in equation (19) is in agreement with the expressions obtained in [10, 11] apart from an overall normalization factor.

4 The $SU(2)$ case

In this section, we shall compute $I(L_{p/r})$ for the gauge group $G = SU(2)$. Then, we will show that in this case our conjecture is true; i.e. when $I(L_{p/r}) \neq 0$, the absolute value $|I(L_{p/r})|$ only depends on p .

For $k \geq 2$, the standard basis of \mathcal{T}_k is $\{\psi[j]\}$; the index j represents the dimension of the irreducible representation described by $\psi[j]$ and $1 \leq j \leq (k-1)$. The matrix elements of X and Y are

$$(X)_{mn} = \frac{i}{\sqrt{2k}} \left[\exp\left(-\frac{i\pi mn}{k}\right) - \exp\left(\frac{i\pi mn}{k}\right) \right] \quad ; \\ (Y)_{mn} = \xi \exp\left(-\frac{i\pi m^2}{2k}\right) \delta_{mn} \quad ; \quad (21)$$

with

$$\xi = \exp(i\pi/2k) \quad . \quad (22)$$

When $k = 1$, one has

$$X = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \quad , \quad Y = \begin{pmatrix} 1 & 0 \\ 0 & i \end{pmatrix} \quad . \quad (23)$$

The algebra \mathcal{T}_1 is isomorphic with \mathcal{T}_3 and it is easy to verify that

$$I_{k=1}(L_{p/r}) = \left[I_{k=3}(L_{p/r}) \right]^* . \quad (24)$$

Therefore, we only need to consider the case $k \geq 2$.

In order to compute $I(L_{p/r})$, we shall derive a recursive relation for the matrix (20); the argument that we shall use has been produced by Jeffrey [11] in a slightly different context. In fact, our final result for $I(L_{p/r})$ is essentially in agreement with the formulae obtained by Jeffrey. Since in our approach the invariance under Kirby moves is satisfied, our derivation of $I(L_{p/r})$ proves that the appropriate expressions given in [10, 11] really correspond to the values of a topological invariant of 3-manifolds.

Let us introduce a few definitions; with the ordered set of integers $\{z_1, z_2, \dots, z_d\}$ one can define the following partial continued fraction decompositions

$$\frac{\alpha_t}{\gamma_t} = z_t - \frac{1}{z_{t-1} - \frac{1}{\ddots - \frac{1}{z_1}}} , \quad (25)$$

where $1 \leq t \leq d$. The integers α_t and γ_t satisfy the recursive relations

$$\alpha_{m+1} = z_{m+1} \alpha_m - \gamma_m, \quad , \quad \alpha_1 = z_1 \quad , \quad \alpha_0 = 1 \quad ; \quad (26)$$

$$\gamma_{m+1} = \alpha_m \quad , \quad \gamma_1 = 1 \quad , \quad (27)$$

and, clearly, $\alpha_d/\gamma_d = p/r$. Finally, let F_t be the matrix

$$F_t = XY^{z_t}XY^{z_{t-1}}X \dots XY^{z_1}X \quad ; \quad (28)$$

by definition, one has $F_d = F(p/r)$.

Lemma 1

The matrix element $(F_t)_{mn}$ is given by

$$(F_t)_{mn} = B_t \sum_{s(m,k,|\alpha_t|)} \left[e^{\frac{i\pi\gamma_t}{2k\alpha_t} \left(s + \frac{n}{\gamma_t}\right)^2} - e^{\frac{i\pi\gamma_t}{2k\alpha_t} \left(s - \frac{n}{\gamma_t}\right)^2} \right] ; \quad (29)$$

$$B_t = \frac{(-i)^{t+1}}{\sqrt{2k|\alpha_t|}} \xi^{z_1+z_2+\dots+z_t} \exp \left\{ -\frac{i\pi}{4} [\text{sign}(\alpha_0\alpha_1) + \dots + \text{sign}(\alpha_{t-1}\alpha_t)] \right\} \\ \exp \left\{ \frac{i\pi n^2}{2k} \left[\frac{1}{\alpha_0\alpha_1} + \dots + \frac{1}{\alpha_{t-2}\alpha_{t-1}} \right] \right\} ; \quad (30)$$

where $s(m, k, |\alpha_t|)$ stands for the sum over a complete residue system modulo $(2k|\alpha_t|)$ with the additional constraint $s \equiv m \pmod{2k}$.

Proof

The proof is based on induction. First of all we need to verify the validity of equations (29) and (30) when $t = 1$. In this case, from the definition (28) one gets

$$(F_1)_{mn} = -\frac{1}{2k} \frac{1}{2} \xi^{z_1} \sum_{s=1}^{2k} e^{-i\pi s^2 z_1/(2k)} \left[e^{-i\pi s(m+n)/k} - e^{-i\pi s(m-n)/k} + \text{c. c.} \right] . \quad (31)$$

Since the sum (31) covers twice a complete residue system modulo k , i.e. $1 \leq s \leq 2k$, a multiplicative factor $1/2$ has been introduced in (31). The change of variables $s \rightarrow -s$ shows that the last two terms in (31) are equal to the first two terms. Therefore, equation (31) can be written as

$$(F_1)_{mn} = -\frac{1}{2k} \xi^{z_1} \sum_{s=1}^{2k} e^{-i\pi s^2 z_1 / (2k)} \left[e^{-i\pi s(m+n)/k} - e^{-i\pi s(m-n)/k} \right] . \quad (32)$$

At this point, one can use the reciprocity formula [19] reported in the appendix and one gets

$$(F_1)_{mn} = \frac{-1}{\sqrt{2k|z_1|}} \xi^{z_1} \exp \left\{ -\frac{i\pi}{4} \text{sign}(\alpha_0 \alpha_1) \right\} \times \\ \times \sum_{v=0}^{|z_1|-1} \left[e^{\frac{i\pi}{2kz_1}(2kv+m+n)^2} - e^{\frac{i\pi}{2kz_1}(2kv+m-n)^2} \right] . \quad (33)$$

By introducing the new variable $s = 2kv + m$, one finds that in equation (33) the variable s covers a complete residue system modulo $(2k|z_1|)$ with the constraint that $s \equiv m \pmod{2k}$. Therefore, equation (33) can be written in the form

$$(F_1)_{mn} = B_1 \sum_{s(m,k,|z_1|)} \left[e^{\frac{i\pi}{2kz_1}(s+n)^2} - e^{\frac{i\pi}{2kz_1}(s-n)^2} \right] . \quad (34)$$

This confirms the validity of equation (29) when $t = 1$. In order to complete the proof, suppose now that (29) is true for a given t ; we shall show that (29) is true also in the case $t + 1$. Indeed, one has

$$(F_{t+1})_{mn} = \sum_{v=1}^k (XY^{z_{t+1}})_{mv} (F_t)_{vn} . \quad (35)$$

From equation (29) one gets

$$(F_{t+1})_{mn} = -B_t \frac{i\xi^{z_{t+1}}}{\sqrt{2k}} \frac{1}{2} \sum_{v=1}^{2k} \sum_{s(v,k,|\alpha_t|)} e^{-\frac{i\pi}{2k} v^2 z_{t+1}} \\ \left[e^{\frac{i\pi\gamma_t}{2k\alpha_t} \left(s - \frac{n}{\gamma_t}\right)^2} e^{-i\pi mv/k} - e^{\frac{i\pi\gamma_t}{2k\alpha_t} \left(s + \frac{n}{\gamma_t}\right)^2} e^{-i\pi mv/k} \right. \\ \left. - e^{\frac{i\pi\gamma_t}{2k\alpha_t} \left(s - \frac{n}{\gamma_t}\right)^2} e^{i\pi mv/k} + e^{\frac{i\pi\gamma_t}{2k\alpha_t} \left(s + \frac{n}{\gamma_t}\right)^2} e^{i\pi mv/k} \right] . \quad (36)$$

Again, the last two terms can be omitted provided one introduces a multiplicative factor 2. Moreover, because of the constraint $v = s \pmod{2k}$, one can set $v = s$, thus

$$(F_{t+1})_{mn} = -B_t \frac{i\xi^{z_{t+1}}}{\sqrt{2k}} e^{\frac{i\pi n^2}{2k\alpha_t \gamma_t}} \sum_{s=0}^{2k|\alpha_t|-1} \\ \left\{ e^{-\frac{i\pi}{2k\alpha_t} [\alpha_{t+1}s^2 + 2(\gamma_{t+1}m+n)s]} - e^{-\frac{i\pi}{2k\alpha_t} [\alpha_{t+1}s^2 + 2(\gamma_{t+1}m-n)s]} \right\} . \quad (37)$$

By using the reciprocity formula, one obtains the final expression for $(F_{t+1})_{mn}$

$$(F_{t+1})_{mn} = -i B_t \xi^{z_{t+1}} \sqrt{\frac{|\alpha_t|}{|\alpha_{t+1}|}} e^{\left(\frac{i\pi n^2}{2k\alpha_t\alpha_{t+1}}\right)} e^{\frac{-i\pi}{4} \text{sign}(\alpha_t\alpha_{t+1})} \sum_{v=1}^{|\alpha_{t+1}|} \left\{ e^{\frac{i\pi\alpha_t}{2k\alpha_{t+1}} \left(2kv+m+\frac{n}{\alpha_t}\right)^2} - e^{\frac{i\pi\alpha_t}{2k\alpha_{t+1}} \left(2kv+m-\frac{n}{\alpha_t}\right)^2} \right\} . \quad (38)$$

In terms of the variable $s = 2kv + m$, equation (38) can be rewritten in the form (29) and this concludes the proof. \spadesuit

From the definition (19) and **Lemma 1** it follows

Theorem 1

Let $SU(2)$ be the gauge group, the 3-manifolds invariant $I_k(L_{p/r})$ for $k \geq 2$ is given by

$$I_k(L_{p/r}) = \sum_{s \pmod{p}} \left\{ \exp \left[\frac{i\pi(r+1)^2}{2pkr} \right] \exp \left[\frac{i2\pi}{p} [rks^2 + (r+1)s] \right] - \exp \left[\frac{i\pi(r-1)^2}{2pkr} \right] \exp \left[\frac{i2\pi}{p} [rks^2 + (r-1)s] \right] \right\} \frac{e^{i\theta_k \sigma(\mathcal{L})} B_d}{a_k} . \quad (39)$$

Proof

According to equation (19), the expression for the matrix element $[F(p/r)]_{11}$ has been written by means of a sum over a complete residue system modulo p . \spadesuit

As shown in equation (39), the expression for $I_k(L_{p/r})$ is rather involved; nevertheless, $|I_k(L_{p/r})|^2$ can be computed explicitly. Let us introduce the modulo- p Croneker delta symbol defined by

$$\delta_p(x) = \begin{cases} 0 & x \not\equiv 0 \pmod{p} \\ 1 & x \equiv 0 \pmod{p} \end{cases} ; \quad (40)$$

where p and x are integers. One can easily verify that, for integer n ,

$$\begin{cases} \delta_p(xn) = \delta_p(x) & \text{if } (n, p) = 1 \\ \delta_{pn}(xn) = \delta_p(x) & \end{cases} . \quad (41)$$

Finally, we shall denote by $\phi(n)$ the Euler function [20] which is equal to the number of residue classes modulo n which are coprime with n .

Theorem 2

The square of the absolute value of $I_k(L_{p/r})$ is given in the following list ; for $p = 2$

$$|I_k(L_{2/1})|^2 = [1 + (-1)^k] \frac{\sin^2 [\pi/(2k)]}{\sin^2 [\pi/k]} ; \quad (42)$$

for $p > 2$ one has :

when p and k are coprime integers, i.e. $(k, p) = 1$,

$$\begin{aligned} \left| I_k(L_{p/r}) \right|^2 &= \frac{1}{2} [1 - (-1)^p] \frac{\sin^2 \left[\pi \left(k^{\phi(p)} - 1 \right) / (kp) \right]}{\sin^2(\pi/k)} + \\ &\quad \frac{1}{2} [1 + (-1)^p] [1 + (-1)^{p/2}] \frac{\sin^2 \left[\pi \left(k^{\phi(p/2)} - 1 \right) / (kp) \right]}{\sin^2(\pi/k)} \quad ; \quad (43) \end{aligned}$$

when the greatest common divisor of p and k is greater than unity, i.e. $(k, p) = g > 1$ and p/g is odd

$$\left| I_k(L_{p/r}) \right|^2 = \frac{g}{4 \sin^2(\pi/k)} [\delta_g(r-1) + \delta_g(r+1)] \quad ; \quad (44)$$

when $(k, p) = g > 1$ and p/g is even

$$\begin{aligned} \left| I_k(L_{p/r}) \right|^2 &= \frac{g}{4 \sin^2(\pi/k)} \left\{ \delta_g(r+1) [1 + (-1)^{kp/2g^2} (-1)^{(r+1)/g}] + \right. \\ &\quad \left. \delta_g(r-1) [1 + (-1)^{kp/2g^2} (-1)^{(r-1)/g}] \right\} \quad . \quad (45) \end{aligned}$$

Proof

From Theorem 1 it follows that the square of the absolute value of the lens space invariant is

$$\left| I_k(L_{p/r}) \right|^2 = a(k)^{-2} (2kp)^{-1} \mathcal{S}(k, p, r) \quad , \quad (46)$$

with

$$\begin{aligned} \mathcal{S}(k, p, r) &= \sum_{s, t \pmod{p}} \left\{ \exp \left\{ \frac{i2\pi}{p} [kr(s^2 - t^2) + (r+1)(s-t)] \right\} \right. \\ &\quad - \exp \left(\frac{i2\pi}{kp} \right) \exp \left\{ \frac{i2\pi}{p} [kr(s^2 - t^2) + r(s-t) + s+t] \right\} \\ &\quad - \exp \left(-\frac{i2\pi}{kp} \right) \exp \left\{ \frac{i2\pi}{p} [kr(s^2 - t^2) + r(s-t) - s-t] \right\} \\ &\quad \left. + \exp \left\{ \frac{i2\pi}{p} [kr(s^2 - t^2) + (r-1)(s-t)] \right\} \right\} \quad . \quad (47) \end{aligned}$$

The indices s and t run over a complete residue system modulo p . When $p = 2$, each sum contains only two terms and the evaluation of (47) is straightforward; the corresponding result is shown in equation (42). Let us now consider the case in which $p > 2$. By means of the change of variables $s \rightarrow s+t$, the sum in t becomes a geometric sum and one obtains

$$\mathcal{S}(k, p, r) = p \sum_{s \pmod{p}} \left\{ \exp \left\{ \frac{i2\pi}{p} [krs^2 + (r+1)s] \right\} \delta_p(2krs) \right.$$

$$\begin{aligned}
& - \exp\left(\frac{i2\pi}{kp}\right) \exp\left\{\frac{i2\pi}{p} [krs^2 + (r+1)s]\right\} \delta_p(2krs + 2) \\
& - \exp\left(\frac{-i2\pi}{kp}\right) \exp\left\{\frac{i2\pi}{p} [krs^2 + (r-1)s]\right\} \delta_p(2krs - 2) \\
& + \exp\left\{\frac{i2\pi}{p} [krs^2 + (r-1)s]\right\} \delta_p(2krs) \Big\} \quad . \quad (48)
\end{aligned}$$

By using properties (41), one can determine the values of s which give contribution to (48). Let us start with $(k, p) = 1$. Clearly, in this case one has

$$\delta_p(2krs) \neq 0 \Rightarrow \begin{cases} s = p & p \text{ odd} \\ s = p, p/2 & p \text{ even} \end{cases} \quad . \quad (49)$$

When $(k, p) = 1$ and p is odd, one gets

$$\delta_p(2krs \mp 2) = \delta_p(krs \mp 1) \quad . \quad (50)$$

The delta gives a non-vanishing contribution if and only if the following congruence is satisfied

$$rks = \pm 1 \pmod{p} \quad . \quad (51)$$

The unique solution [20] to (51) is given by

$$s = \pm (rk)^{\phi(p)-1} \quad . \quad (52)$$

When $(k, p) = 1$ and p is even, one finds two solutions

$$s_1 = \pm (rk)^{\phi(p/2)-1}, \quad s_2 = \pm (rk)^{\phi(p/2)-1} + p/2 \quad . \quad (53)$$

Let us now examine the case $(p, k) = g > 1$. We introduce the integer β defined by $p = g\beta$. For β odd, one has

$$\delta_p(2krs) = \delta_\beta(s) \quad . \quad (54)$$

Within the residues of a complete system modulo p , the values of s giving non-vanishing contribution are of the form $s = \alpha\beta$ with $1 \leq \alpha \leq g$. When β is even, one gets

$$\delta_p(2krs) = \delta_\beta(2s) = \delta_{\beta/2}(s) \quad . \quad (55)$$

The solutions of the associated congruence are

$$s = \alpha \frac{\beta}{2} \quad 1 \leq \alpha \leq 2g \quad . \quad (56)$$

When $(k, p) = g > 1$ and p is odd, $\delta_p[2r(ks \pm 1)]$ does not contribute because $rks = \pm 1 \pmod{p}$ has no solutions. On the other hand, if p is even we have

$$\delta_p[(2krs \pm 2)] = \delta_{p/2}(rks \pm 1) \quad . \quad (57)$$

The delta function (57) is non-vanishing when $(p/2, k) = 1$ and, in this case, the two solutions are $s_1 = \pm(rk)^{\phi(p/2)-1}$ and $s_2 = s_1 + p/2$. This exhausts the analysis of the modulo p Croneker deltas when $p > 2$.

At this stage, Theorem 2 simply follows from the substitution of the values of s for which the various Croneker deltas modulo p are non vanishing. In the case $(k, p) = 1$ and p odd, the algebraic manipulations are straightforward. When $(k, p) = 1$ and p even, the evaluation of (48) needs some care. In this case, one has to deal with factors of the form

$$\exp \left[\frac{i\pi}{b} (a^{\phi(b)} - 1) \right] \quad ; \quad (58)$$

with $b > 2$ even and $(a, b) = 1$. In appendix B, it is shown that terms of the type (58) are trivial because actually

$$a^{\phi(b)} \equiv 1 \pmod{2b} \quad . \quad (59)$$

Finally, the derivation of equations (44) and (45) is straightforward. ♠

Let us now consider the dependence of $|I(L_{p/r})|^2$ on r . As shown in equations (44) and (45), $|I(L_{p/r})|^2$ depends on r . However, this dependence is rather peculiar: when $I(L_{p/r}) \neq 0$, $|I(L_{p/r})|^2$ does not depend on r . Indeed, when expression (44) is different from zero, its values are given by

$$0 \neq (44) = \begin{cases} \sin^{-2}(\pi/k) & \text{for } g = 2 ; \\ (g/4) \sin^{-2}(\pi/k) & \text{for } g > 2 . \end{cases} \quad (60)$$

Similarly, when expression (45) is different from zero, its value is given by

$$0 \neq (45) = \frac{g}{2 \sin^2(\pi/k)} \quad . \quad (61)$$

To sum up, when $I(L_{p/r}) \neq 0$, $|I(L_{p/r})|^2$ only depends on p and, therefore, it is a function of the fundamental group $\pi_1(L_{p/r}) = Z_p$. Thus, Theorem 2 proves the validity of our conjecture for the lens spaces when the gauge group is $SU(2)$.

5 The $SU(3)$ case

In this section we shall present numerical computations confirming the validity of our conjecture for lens spaces when the gauge group is $SU(3)$. As in the $SU(2)$ case, the $SU(3)$ Chern-Simons field theory can be solved explicitly in any closed, connected and orientable three-manifold [16]. The general surgery rules for $SU(3)$ and for any integer k have been derived in [16]. In particular, it turns out that

$$I_{k=1}(L_{p/r}) = \left[I_{k=2}(L_{p/r}) \right]^* = I_{k=4}(L_{p/r}) \quad . \quad (62)$$

Therefore, we only need to consider the case $k \geq 3$. For $k \geq 3$, the matrices which give a projective representation of the modular group have the following form

$$X_{(m,n)(a,b)} = \frac{i}{k\sqrt{3}} q^{-2} q^{-[(m+n)(a+b+3)+(m+3)b+(n+3)a]/3}$$

$$\left[1 + q^{(n+1)(a+b+2)+(m+1)(b+1)} + q^{(m+1)(a+b+2)+(n+1)(a+1)} - q^{(m+1)(b+1)} - q^{(n+1)(a+1)} - q^{(m+n+2)(a+b+2)} \right] ; \quad (63)$$

$$Y_{(a,b)(m,n)} = q^{[m^2+n^2+mn+3(m+n)]/3} \delta_{am} \delta_{bn} ; \quad (64)$$

$$C_{(a,b)(m,n)} = \delta_{an} \delta_{bm} ; \quad (65)$$

where each irreducible representation of $SU(3)$ has been denoted by a couple of nonnegative integers (m, n) (Dynkin labels).

By using equation (18), we have computed $I_k(L_{p/r})$ numerically for some examples of lens spaces. In particular, we have worked out the value of the invariant for the lens spaces $L_{p/r}$, with $p \leq 20$ and $3 \leq k \leq 50$. In all these cases, the results are in agreement with our conjecture.

Our calculations have been performed on a Pentium based PC running Linux. For instance, the results of the computations for the cases $L_{8/1}$, $L_{8/3}$, $L_{15/1}$, $L_{15/2}$, $L_{15/4}$ with $3 \leq k \leq 50$ are shown in Tables 1, 2, 3, 4, 5. The spaces $L_{8/1}$ and $L_{8/3}$ are not homotopically equivalent; as shown in Tables 1 and 2, the phase of the invariant distinguishes these two manifolds. The case in which $p = 15$ is more interesting because there are two different spaces belonging to the same homotopy class; $L_{15/1}$ and $L_{15/4}$ are homotopically equivalent and $L_{15/2}$ represents the other homotopy class. The phase of the invariant distinguishes the manifolds of the same homotopy class.

6 Conclusions

In this article, we have presented some arguments and numerical results supporting the conjecture that, for nonvanishing $I(M)$, the absolute value $|I(M)|$ only depends on the fundamental group $\pi_1(M)$. Since the Turaev-Viro invariant [21] coincides [3] with $|I(M)|^2$, our conjecture gives some hints on the topological interpretation of the Turaev-Viro invariant. For the gauge group $SU(2)$, $|I(M)|^2$ can be understood as the improved partition function of the Euclidean version of (2+1) gravity with positive cosmological constant [22, 23]. In this case, our conjecture suggests that, for instance, the semiclassical limit is uniquely determined by the fundamental group of the universe.

Finally, one may ask for which values of k the equality $I_k(M) = 0$ is satisfied and what the meaning of this fact is. The complete solution to this problem is not known. From the field theory point of view, gauge invariance of the factor $\exp(iS_{CS})$ (where S_{CS} is the Chern-Simons action) in the functional measure gives nontrivial constraints on the admissible values of k in a given manifold M . In certain cases [9] one finds that, in correspondence with the “forbidden” values of k , the invariant $I_k(M)$ vanishes. So, it is natural to expect that $I_k(M) = 0$ is related to a breaking of gauge invariance for large gauge transformations. From the mathematical point of view, $I_k(M) = 0$ signals the absence of the natural extension of $E(\mathcal{L})$ to an invariant $E_M(\mathcal{L})$ of links in the manifold M . More precisely, when $I_k(M) \neq 0$ for fixed integer k , one can define [13] an invariant $E_M(\mathcal{L})$ of oriented, framed and

coloured links $\{\mathcal{L} \subset M\}$ with the following property: if the link \mathcal{L} belongs to a three-ball embedded in M , then one has $E_M(\mathcal{L}) = E(\mathcal{L})$. The values of the invariant $E_M(\mathcal{L})$ correspond to the vacuum expectation values of the Wilson line operators associated with links in the manifold M . When $I_k(M) = 0$, the invariant $E_M(\mathcal{L})$ cannot be constructed; consequently, for these particular values of k , the quantum Chern-Simons field theory is not well defined in M .

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Appendix A

The generalized Gauss sums have a very useful property which can be expressed by means of the so-called reciprocity formula [19]

$$\sum_{n=0}^{|c|-1} e^{i\frac{\pi}{c}(an^2+bn)} = \sqrt{\left|\frac{c}{a}\right|} e^{i\frac{\pi}{4ac}(|ac|-b^2)} \sum_{n=0}^{|a|-1} e^{-i\frac{\pi}{a}(cn^2+bn)} \quad , \quad (66)$$

where the integers a, b, c satisfy the relations

$$ac \neq 0 \quad , \quad ac + b \text{ is even} \quad . \quad (67)$$

Appendix B

Lemma 2 *Let a, b two integers, with $(a, b) = 1$ and $b > 2$ even; one has*

$$a^{\phi(b)} \equiv 1 \pmod{2b} \quad . \quad (68)$$

Proof

The proof consists of two parts: firstly, it is shown by induction that Lemma 2 holds when $b = 2^m$ with $m > 1$ integer. Secondly, equation (68) is proved when $b = 2^m c$ with $m \geq 1$ and c odd integer.

Since b is even, a is clearly odd and can be written in the form $a = (2f + 1)$. When b is of the type $b = 2^m$, the condition $b > 2$ implies that $m \geq 2$. Let us now consider the case $m = 2$; one has $\phi(b) = \phi(2^2) = 2$, therefore

$$a^{\phi(b)} = (2f + 1)^2 = 1 + 4f(f + 1) \equiv 1 \pmod{2^3} \quad . \quad (69)$$

Thus, **Lemma 2** is satisfied when $b = 2^2$. Suppose now that equation (68) holds when $b = 2^n$ for a certain n . We need to prove that (68) is true also for $b = 2^{(n+1)}$. Indeed, $\phi(2^{n+1}) = 2^n$ and one gets

$$(2f + 1)^{\phi(2^{n+1})} = \left[(2f + 1)^{\phi(2^n)} \right]^2 \quad . \quad (70)$$

By using the induction hypothesis

$$(2f + 1)^{\phi(2^n)} = 1 + N 2^{n+1} \quad , \quad (71)$$

one finds

$$\left[(2f + 1)^{\phi(2^n)} \right]^2 = 1 + 2^{n+2} N (1 + 2^n N) \equiv 1 \pmod{2^{n+2}} . \quad (72)$$

Therefore, equation (68) is also satisfied when $b = 2^{(n+1)}$. To sum up, for $m > 1$ and a odd, one has

$$a^{\phi(2^m)} \equiv 1 \pmod{2^{m+1}} . \quad (73)$$

Let us now consider the general case in which $b = 2^m c$ with c odd integer. From Euler Theorem [20] it follows that

$$a^{\phi(b)} \equiv 1 \pmod{b} \Rightarrow a^{\phi(b)} \equiv 1 \pmod{c} . \quad (74)$$

On the other hand, $\phi(2^m c) = \phi(2^m) \phi(c)$ and, for $m > 1$, equation (73) implies

$$a^{\phi(b)} = a^{\phi(c) \phi(2^m)} \equiv 1 \pmod{2^{m+1}} . \quad (75)$$

Since $(2^{m+1}, c) = 1$, from equations (74) and (75) one gets

$$a^{\phi(b)} \equiv 1 \pmod{2^{m+1} c} \equiv 1 \pmod{2b} . \quad (76)$$

Finally, we need to consider the case $b = 2c$. Since $\phi(c)$ is even, one gets

$$a^{\phi(2c)} = [1 + 4f(f+1)]^{\phi(c)/2} \equiv 1 \pmod{2^2} . \quad (77)$$

Equations (73) and (77) imply

$$a^{\phi(2c)} \equiv 1 \pmod{2^2 c} . \quad (78)$$

This concludes the proof. 

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•	$L_{8/1}$	•
k	I_k	$ I_k $
3	1.000000000 - i 0.000000175	1.000000000
4	-1.000000000 + i 0.000000012	1.000000000
5	-0.499999839 + i 1.538841821	1.618033989
6	-2.000000000 + i 0.000000175	2.000000000
7	-1.000000000 - i 0.000000095	1.000000000
8	-6.828427084 + i 6.828427165	9.656854249
9	-0.499999950 + i 0.866025433	1.000000000
10	-4.236067816 + i 3.077683759	5.236067977
11	-2.073846587 - i 14.423920506	14.572244935
12	-7.464102180 - i 12.928202904	14.928203230
13	-12.373524802 - i 17.926145664	21.781891892
14	18.195669358 + i 0.000000868	18.195669358
15	5.657005398 + i 4.110054701	6.992443043
16	63.431390926 + i 26.274142180	68.657642707
17	6.721172941 + i 2.603796085	7.207906752
18	15.581719525 + i 26.988328071	31.163437478
19	-69.185356387 - i 11.544994773	70.142001987
20	-66.118464248 + i 0.000001734	66.118464248
21	-90.016155013 + i 0.000000715	90.016155013
22	43.367008373 - i 50.048195295	66.223253224
23	22.973052202 - i 3.157573698	23.189036183
24	219.054514271 - i 58.695485329	226.781922164
25	23.000602198 - i 5.905551129	23.746646829
26	84.434763344 + i 44.314782640	95.357376335
27	-185.409752744 + i 67.483626877	197.308936212
28	-161.491033989 + i 77.769978391	179.241523084
29	-214.342425435 + i 99.165358161	236.170369862
30	50.544948881 - i 155.561366312	163.566899299
31	47.834849646 - i 26.550506056	54.709251617
32	443.615385766 - i 296.414325177	533.531688523
33	46.894822945 - i 30.137471278	55.743982582
34	211.662329441 + i 39.566544008	215.328709440
35	-344.610722364 + i 250.374335362	425.962272715
36	-290.376668930 + i 243.654963011	379.059824907
37	-381.345093602 + i 307.914657384	490.138262785
38	27.064369107 - i 326.618342223	327.737732877
39	79.852315000 - i 70.742976321	106.681586554
40	734.287201006 - i 734.287220264	1038.438931957
41	78.053570702 - i 75.119028091	108.329258655
42	408.590935390 - i 0.000001624	408.590935390
43	-545.541472393 + i 565.843251992	785.998781122
44	-452.077098514 + i 521.724781996	690.340822456
45	-590.050989168 + i 655.318028318	881.817377951
46	-39.324647251 - i 574.905929557	576.249299975
47	118.947578576 - i 140.691854636	184.235513433
48	1090.316030520 - i 1420.927547540	1791.039960963
49	116.363242798 - i 145.914887153	186.632147733
50	687.196328608 - i 86.813088226	692.658145364

•	$L_{8/3}$	•
k	I_k	$ I_k $
3	1.000000000 + i 0.000000000	1.000000000
4	-1.000000000 + i 0.000000000	1.000000000
5	1.309016994 - i 0.951056516	1.618033989
6	-2.000000000 + i 0.000000000	2.000000000
7	-0.623489802 + i 0.781831482	1.000000000
8	0.000000000 + i 0.000000000	0.000000000
9	-0.500000000 + i 0.866025404	1.000000000
10	1.618033989 + i 4.979796570	5.236067977
11	6.053529319 - i 13.255380237	14.572244935
12	-7.464101615 + i 12.928203230	14.928203230
13	7.723965314 - i 20.366422715	21.781891892
14	-16.393731622 + i 7.894805057	18.195669358
15	-2.160783733 + i 6.650208521	6.992443043
16	0.000000000 + i 0.000000000	0.000000000
17	-1.972537314 + i 6.932749548	7.207906752
18	15.581718739 + i 26.988328525	31.163437478
19	17.218843527 - i 67.995675380	70.142001987
20	-20.431729095 + i 62.882396270	66.118464248
21	20.030478885 - i 87.759262069	90.016155013
22	-55.710545730 + i 35.802993757	66.223253224
23	-4.717948848 + i 22.704016336	23.189036183
24	0.000000000 + i 0.000000000	0.000000000
25	-4.449677900 + i 23.326028428	23.746646829
26	54.169163837 + i 78.477582217	95.357376335
27	34.262337211 - i 194.311370120	197.308936212
28	-39.884991120 + i 174.747563877	179.241523084
29	38.208113963 - i 233.059184818	236.170369862
30	-132.328401250 + i 96.142211171	163.566899299
31	-8.284500381 + i 54.078362271	54.709251617
32	0.000000000 + i 0.000000000	0.000000000
33	-7.933195866 + i 55.176589215	55.743982582
34	129.764538515 + i 171.836019661	215.328709440
35	57.178306982 - i 422.107212669	425.962272715
36	-65.823047822 + i 373.301054424	379.059824907
37	62.256293514 - i 486.168356194	490.138262785
38	-258.631121471 + i 201.300681961	327.737732877
39	-12.859044288 + i 105.903757675	106.681586554
40	0.000000000 + i 0.000000000	0.000000000
41	-12.423570453 + i 107.614511930	108.329258655
42	254.752281347 + i 319.449256739	408.590935390
43	85.965636475 - i 781.283554973	785.998781122
44	-98.245742501 + i 683.314148273	690.340822456
45	92.175015400 - i 876.986690089	881.817377951
46	-447.003088251 + i 363.663986140	576.249299975
47	-18.441181139 + i 183.310248618	184.235513433
48	0.000000000 + i 0.000000000	0.000000000
49	-17.920983557 + i 185.769741658	186.632147733
50	441.516918550 + i 533.702273720	692.658145364

•	$L_{15/1}$	•
k	I_k	$ I_k $
3	1.000000000 - i 0.000000175	1.000000000
4	0.000000021 + i 1.732050808	1.732050808
5	-2.665351925 + i 1.936491953	3.294556414
6	3.000000303 + i 3.464101353	4.582575695
7	-0.000000165 + i 1.732050808	1.732050808
8	-1.732050808 + i 0.000000010	1.732050808
9	-0.907604426 - i 11.866568847	11.901226911
10	-5.959909504 - i 18.342712091	19.286669182
11	-17.245203220 + i 14.943053456	22.818673947
12	-11.196152781 - i 8.196151933	13.875544804
13	0.000000084 - i 15.347547346	15.347547346
14	0.000000083 - i 1.732050808	1.732050808
15	-101.423006915 - i 32.954328677	106.642459228
16	-1.224744868 + i 1.224744875	1.732050808
17	-20.645987906 + i 15.591127116	25.871607244
18	-40.127945922 - i 30.808776018	50.590836361
19	65.239497521 - i 83.819706393	106.216454548
20	-115.811330427 - i 84.141852139	143.150674244
21	-53.061367118 - i 135.569663547	145.583798394
22	36.010672960 + i 16.445523443	39.588177633
23	-40.070955963 - i 2.740927872	40.164588848
24	164.290883844 - i 129.064834808	208.923972053
25	274.923532195 - i 34.730921473	277.108616721
26	0.000000762 - i 277.056941014	277.056941014
27	152.288761117 + i 30.720691710	155.356453557
28	-0.000003253 + i 136.433611353	136.433611353
29	-4.270422302 + i 12.674160517	13.374260781
30	485.145409358 + i 667.745345688	825.378649414
31	13.416605095 + i 0.680413518	13.433847358
32	164.960256203 + i 68.328775084	178.551694562
33	-82.729230504 + i 287.059281883	298.742626511
34	-538.981501170 - i 268.380890132	602.104111256
35	-415.659227492 + i 629.696787632	754.513510650
36	-681.771583909 + i 223.335013764	717.419696551
37	101.630605413 - i 150.367371847	181.491395038
38	-59.482939675 + i 173.267881065	183.193828283
39	-279.481438371 - i 847.784737546	892.663898458
40	347.379313920 - i 1069.123643311	1124.143119192
41	-941.842709163 - i 512.157840150	1072.088308877
42	399.545316356 - i 429.453517605	586.572061733
43	390.071778264 + i 279.072428091	479.622155784
44	24.267771316 + i 37.761389387	44.887049949
45	2753.539308039 + i 289.408610795	2768.706568944
46	32.920210846 - i 30.745331135	45.044596443
47	536.002877882 - i 206.437637985	574.382784800
48	394.055675294 + i 817.737030229	907.729985094
49	-1754.712300120 + i 400.501606784	1799.837990828
50	137.556258644 + i 2186.393963508	2190.716843400

•	$L_{15/2}$	•
k	I_k	$ I_k $
3	1.000000000 + i 0.000000000	1.000000000
4	0.000000000 - i 1.732050808	1.732050808
5	0.000000000 + i 0.000000000	0.000000000
6	3.000000000 - i 3.464101615	4.582575695
7	0.000000000 - i 1.732050808	1.732050808
8	1.732050808 + i 0.000000000	1.732050808
9	10.730551990 - i 5.147276559	11.901226911
10	0.000000000 + i 0.000000000	0.000000000
11	-12.336706536 + i 19.196290072	22.818673947
12	-11.196152423 + i 8.196152423	13.875544804
13	14.350206054 - i 5.442315293	15.347547346
14	0.000000000 + i 1.732050808	1.732050808
15	0.000000000 + i 0.000000000	0.000000000
16	1.224744871 - i 1.224744871	1.732050808
17	9.345902508 + i 24.124555285	25.871607244
18	-6.617211192 - i 50.156208387	50.590836361
19	50.553444640 - i 93.414583721	106.216454548
20	0.000000000 + i 0.000000000	0.000000000
21	-53.061366041 + i 135.569663969	145.583798394
22	-11.153278505 + i 37.984578277	39.588177633
23	-29.353726021 - i 27.414466365	40.164588848
24	-164.290886665 - i 129.064831217	208.923972053
25	0.000000000 + i 0.000000000	0.000000000
26	228.013392388 + i 157.386281027	277.056941014
27	56.698638283 + i 144.640561664	155.356453557
28	0.000000000 - i 136.433611353	136.433611353
29	11.816320486 + i 6.264616638	13.374260781
30	0.000000000 + i 0.000000000	0.000000000
31	-1.359079795 - i 13.364922631	13.433847358
32	164.960256101 + i 68.328775330	178.551694562
33	-224.792217910 - i 196.762841162	298.742626511
34	-110.636340119 - i 591.852144574	602.104111256
35	0.000000000 + i 0.000000000	0.000000000
36	147.472006710 + i 702.099015977	717.419696551
37	45.731849880 + i 175.635202563	181.491395038
38	-177.588145856 - i 44.971426177	183.193828283
39	-875.291194999 - i 175.254556482	892.663898458
40	0.000000000 + i 0.000000000	0.000000000
41	1052.478012596 + i 204.116082250	1072.088308877
42	399.545318063 + i 429.453516017	586.572061733
43	-171.335849479 - i 447.974819607	479.622155784
44	44.430164502 + i 6.388093254	44.887049949
45	0.000000000 + i 0.000000000	0.000000000
46	-17.945816315 - i 41.315412930	45.044596443
47	571.498128245 + i 57.493242102	574.382784800
48	-817.737034535 - i 394.055666358	907.729985094
49	-780.920437266 - i 1621.597997004	1799.837990828
50	0.000000000 + i 0.000000000	0.000000000

•	$L_{15/4}$	•
k	I_k	$ I_k $
3	1.000000000 + i 0.000000000	1.000000000
4	0.000000000 + i 1.732050808	1.732050808
5	-1.018073921 - i 3.133309346	3.294556414
6	3.000000000 + i 3.464101615	4.582575695
7	-0.751508681 - i 1.560523855	1.732050808
8	-1.732050808 + i 0.000000000	1.732050808
9	10.730551990 + i 5.147276559	11.901226911
10	-15.603243133 - i 11.336419711	19.286669182
11	17.245203123 + i 14.943053568	22.818673947
12	-11.196152423 - i 8.196152423	13.875544804
13	3.672908488 + i 14.901575513	15.347547346
14	-1.688624678 + i 0.385417563	1.732050808
15	0.000000000 + i 0.000000000	0.000000000
16	-1.224744871 + i 1.224744871	1.732050808
17	-17.429589094 - i 19.119348456	25.871607244
18	-6.617211192 + i 50.156208387	50.590836361
19	0.000000000 - i 106.216454548	106.216454548
20	-44.235991098 + i 136.144381552	143.150674244
21	72.909410760 - i 126.011349400	145.583798394
22	-36.010673013 + i 16.445523326	39.588177633
23	-10.836276386 + i 38.675176941	40.164588848
24	164.290886665 - i 129.064831217	208.923972053
25	-257.649075864 + i 102.010485575	277.108616721
26	275.036883975 - i 33.395523912	277.056941014
27	-153.611719961 + i 23.217819719	155.356453557
28	106.668092622 + i 85.064965309	136.433611353
29	-9.197471902 + i 9.709653035	13.374260781
30	0.000000000 + i 0.000000000	0.000000000
31	-4.021598499 + i 12.817761129	13.433847358
32	-164.960256101 - i 68.328775330	178.551694562
33	85.599713692 + i 286.216431937	298.742626511
34	-217.505092368 - i 561.445362956	602.104111256
35	33.851120653 + i 753.753765751	754.513510650
36	147.472006710 - i 702.099015977	717.419696551
37	-136.240563896 + i 119.906777214	181.491395038
38	0.000000000 + i 183.193828283	183.193828283
39	538.949599873 - i 711.605343156	892.663898458
40	-909.450887536 + i 660.754746927	1124.143119192
41	1008.985242455 - i 362.383943545	1072.088308877
42	-546.310790198 + i 213.568031595	586.572061733
43	426.548198677 + i 219.303548819	479.622155784
44	-24.267771377 + i 37.761389348	44.887049949
45	0.000000000 + i 0.000000000	0.000000000
46	-6.133571758 + i 44.625048641	45.044596443
47	-558.735830232 - i 133.153503483	574.382784800
48	394.055666358 + i 817.737034536	907.729985094
49	-883.212092863 - i 1568.232505801	1799.837990828
50	410.499402001 + i 2151.913225229	2190.716843400